

Non-Gaussian quasi-likelihood estimation of jump processes

Hiroki Masuda

Graduate School of Mathematics, Kyushu University, Japan

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Brief summary

“Inference for a class of Stochastic Differential Equations (SDE)”

- When observing a discrete-time but high-frequency sample

$$X_0, X_{h_n}, X_{2h_n}, \dots, X_{nh_n} \quad (h_n \rightarrow 0)$$

from the semi-parametric Lévy driven SDE

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t,$$

how can we estimate $\theta_0 = (\alpha_0, \gamma_0)$, the true value of $\theta := (\alpha, \gamma)$?

- We will provide an estimator $\hat{\theta}_n = (\hat{\alpha}_n, \hat{\gamma}_n)$ s.t.

$$\left\{ \left(\sqrt{nh_n}^{1-1/\beta} (\hat{\alpha}_n - \alpha_0), \sqrt{n} (\hat{\gamma}_n - \gamma_0) \right) \right\}_{n \in \mathbb{N}} \text{ is asymp. normal,}$$

with β denoting the Blumental-Gettoor index of the Lévy process Z .

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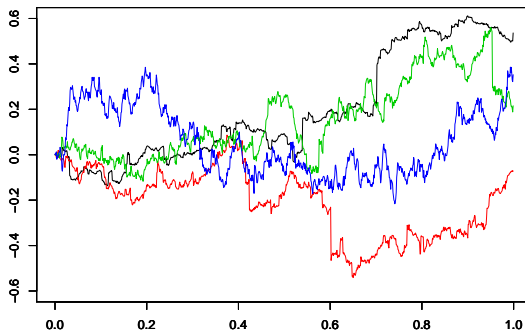
- ▶ Jump process in modelling time-varying phenomena
- ▶ Gaussian Quasi-Likelihood Estimator (GQLE) for discretely observed Lévy driven SDE.
- ▶ A simple way for testing noise normality.
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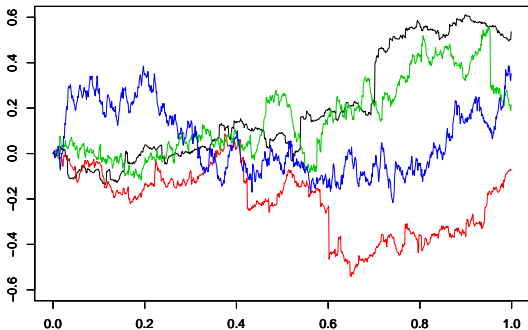
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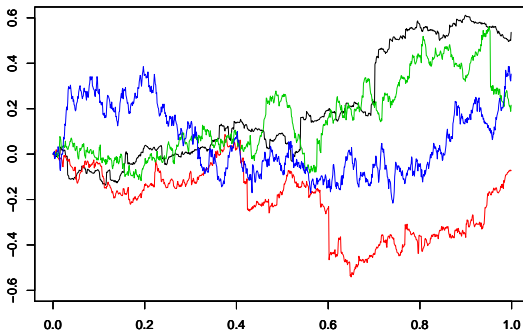
Statistics for SDE models



- **Time-varying phenomena** ← “Stochastic process (SDE) models”
 - ▶ Mostly, data series exhibits dependence.
 - ▶ In real world, data is observed at discrete time instants.



- **“Parameter estimation” is a standing problem in statistics.**
 - ▶ We want a good estimation procedure for a model in question.
- ⇒ **“Estimation of continuous-time structure from discrete-time sample”.**



- **A central issues in stochastic process modelling:**

- ▶ **Continuous?**
- ▶ **Including jumps?**
- ▶ **...or, continuous with jumps?**

Why including jumps?

- **Lévy process in finance (Cont and Tankov (2004)):** e.g.,
 - ▶ **Non-Gaussian stable...** Mandelbrot (1963)
 - ▶ **Normal inverse Gaussian...** Barndorff-Nielsen (1995)
 - ▶ **Hyperbolic...** Eberlein and Keller (1995)
 - ▶ **Generalized hyperbolic...** Prause (1999), Raible (2000)
 - ▶ **CGMY (tempered stable)...** Carr et al. (2002)
 - ▶ **Bilateral gamma...** Küchler and Tappe (2008)
- **Also, signal processing, turbulence, physical science, etc.**
 - ▶ **Non-Gaussian stable...** e.g., Nikias and Shao (1995)
 - ▶ **Semi-heavy tail distributions...** Barndorff-Nielsen (1995)
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⇒ Needs for statistics for jump processes

Non-Gaussian behavior in small time

- In high-frequency data framework, jumps may be more conspicuous.
- Empirical evidence in financial returns, Grabchak and Samorodnitsky (2010):
 - ▶ Distribution tails appear to become:
 - ★ less heavy for less frequent (e.g. monthly) returns,
 - ★ than for more frequent (e.g. daily) returns.
 - ▶ Tempered heavy-tail models are reasonable.

Maximum-Likelihood Estimation for Markov models

- **Maximum-Likelihood Estimator (MLE) is theoretically preferred.**
- Data Y_{t_1}, \dots, Y_{t_n} from a Markov process (Y_t)
- The MLE is defined to be the “argmax” of the log-likelihood function

$$\theta \mapsto \log p_\theta(Y_{t_1}, \dots, Y_{t_n}) = \sum_{j=1}^n \log p_\theta(Y_{t_j} | Y_{t_{j-1}}).$$

- For Y SDE, the transition density $p_\theta(y|x)$ is mostly unknown. What proxy can we make use of? How can we proceed in practice?

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Gaussian Quasi-Likelihood Estimator (GQLE)

- Consists of fitting one-step conditional mean and variances:
 - Originally due to Wedderburn (1974);
 - A kind of generalized method of moments.

To formulate the estimation procedure, it is enough to have

$$E[Y_{t_j} | Y_{t_{j-1}}] = m_{j-1}(\theta) \text{ and } \text{Var}[Y_{t_j} | Y_{t_{j-1}}] = v_{j-1}(\theta).$$

explicitly.

- The GQLE is formally given by the argmax of

$$\theta \mapsto \sum_{j=1}^n \log \left\{ \frac{1}{\sqrt{v_{j-1}(\theta)}} \phi(Y_{t_j} - m_{j-1}(\theta)) \right\},$$

ϕ the $\mathcal{N}(0, 1)$ -density.

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 - ▶ GARCH type model, Straumann and Mikosch (2006),

$$Y_n = \sigma_n \epsilon_n, \quad n \in \mathbb{N},$$

$$\sigma_n = \alpha_0 + \sum_{i=1}^p \alpha_i Y_{n-i}^2 + \sum_{j=1}^q \beta_j \sigma_{n-j}^2.$$

- ▶ Multivariate causal time series, Bardet and Wintenburger (2009),

$$Y_n = M_\theta(Y_{n-1}, Y_{n-2}, \dots) \epsilon_n + f_\theta(Y_{n-1}, Y_{n-2}, \dots).$$

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- **Question.** How about using GQLE methodology for the SDE model...?

GQLE for discretely observed Lévy driven SDE *

- Based on $X_{h_n}, X_{2h_n}, \dots, X_{nh_n}$ stemming from the ergodic

$$dX_t = a(X_t, \alpha)dt + c(X_t, \gamma)dZ_t,$$

we want to estimate $\theta = (\alpha, \gamma)$, where Z is a Lévy process s.t. $E[Z_t] = 0$ and $E[Z_t^2] = t$.

- “Aggressive” approximation $\mathcal{L}(Z_{h_n}) \approx \mathcal{N}(0, h_n)$ for small h_n :

$$\begin{aligned} X_{jh_n} &\approx X_{(j-1)h_n} + a(X_{(j-1)h_n}, \alpha_0)h_n \\ &\quad + c(X_{(j-1)h_n}, \gamma_0)(Z_{jh_n} - Z_{(j-1)h_n}) \\ &\sim \mathcal{N}(X_{(j-1)h_n} + a(X_{(j-1)h_n}, \alpha_0)h_n, c(X_{(j-1)h_n}, \gamma_0)^2 h_n), \end{aligned}$$

making the GQLE procedure explicit.

*M (2010, preprint) and the references therein.

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Resulting phenomenon and a practical caution

$$dX_t = a(X_t, \alpha)dt + c(X_t, \gamma)dZ_t$$

- The GQLE $\hat{\theta}_n = (\hat{\alpha}_n, \hat{\gamma}_n)$ are asymptotically normal:

$$\left(\sqrt{nh_n}(\hat{\alpha}_n - \alpha_0), \sqrt{n}(\hat{\gamma}_n - \gamma_0) \right) \rightarrow^d \mathcal{N}(0, V') \quad \text{if } \nu(\mathbb{R}) = 0;$$

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where ν is the Lévy measure of Z .

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Test statistics for the noise normality

$$\mathcal{T}_n := \frac{n}{6} \left\{ \hat{\Phi}_n^{(3)} - \frac{3\sqrt{h_n}}{n} \sum_{j=1}^n \partial_x c(X_{(j-1)h_n}, \hat{\gamma}_n) \right\}^2 + \frac{n}{24} (\hat{\Phi}_n^{(4)} - 3)^2$$

$$\hat{\epsilon}_{nj} := \frac{X_{jh_n} - X_{(j-1)h_n} - a(X_{(j-1)h_n}, \hat{\alpha}_n)h_n}{c(X_{(j-1)h_n}, \hat{\gamma}_n)\sqrt{h_n}}, \quad \bar{\epsilon}_n := \frac{1}{n} \sum_{j=1}^n \hat{\epsilon}_{nj},$$

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- Consistent and asymptotically distribution-free test:

- ▶ $\mathcal{T}_n \xrightarrow{d} \chi^2(2)$ under $\mathcal{H}_0 : \nu(\mathbb{R}) = 0$;
- ▶ $\mathcal{T}_n \xrightarrow{P} \infty$ under $\mathcal{H}_1 : \nu(\mathbb{R}) \in (0, \infty]$.

- We may proceed as follows: Using \mathcal{T}_n with the GQLE,

- ▶ \mathcal{H}_0 not rejected \Rightarrow follow diffusion estimation procedures,
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Some important previous studies, some remarks

- **Jump detection filter may work well.**
(Mancini, Shimizu and Yoshida, Shimizu, Ogihara and Yoshida.)
 - ▶ Asymptotically efficient, may work well for compound Poisson jumps.
 - ▶ In principle, the coexistence of Wiener and Poisson parts makes estimation problem difficult when pursuing estimation efficiency.
- **What will theoretically occur in general?**
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Our goal of this talk is to

- Provide an estimator of the true value of $\theta = (\alpha, \gamma)$ in

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

based on $X_0, X_{h_n}, X_{2h_n}, \dots, X_{nh_n}$ ($h_n \rightarrow 0$).

- We want to deal with pure-jump Z with higher degree of activity; e.g. Generalized hyperbolic, Meixner, CGMY, etc.
- We here do not adopt:
 - ▶ **the GQLE**, unsatisfactory while usable, in the presence of any jump;
 - ▶ **the jump detection filter approach**, a nice device with a good choice of fine-tuning parameter
 - ★ under the presence of a Wiener part,
 - ★ when jump activity is finite (or moderate).

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- ▶ Gaussian Quasi-Likelihood Estimator (GQLE) for discretely observed Lévy driven SDE.
- ▶ A simple way for testing noise normality.
- ▶ Description of our goal

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- ▶ Assumptions
- ▶ Construction of our estimator
- ▶ Asymptotics: main claim
- ▶ Simulation experiments

③ Summary and concluding remarks

Non-Gaussian Quasi-Likelihood Estimation (NGQLE)

Target:

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t, \quad \eta := \mathcal{L}(X_0)$$

- Z is a **pure-jump Lévy process of infinite activity**.
- The parameter $\theta := (\alpha, \gamma) \in \Theta_\alpha \times \Theta_\gamma = \Theta \subset \mathbb{R}^p$,
a bounded convex domain, the true value $\theta_0 := (\alpha_0, \gamma_0) \in \Theta$.

Notation:

- $\Delta_j Y := Y_{jh_n} - Y_{(j-1)h_n}$ for a process Y ;
- $f_{j-1}(\theta) := f(X_{(j-1)h_n}, \theta)$ for any function of the form $f(x, \theta)$.

A1. Regularity of the coefficients

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- ① a and c are smooth in $\mathbb{R} \times \Theta$.
 - ② $a(\cdot, \alpha_0)$ and $c(\cdot, \gamma_0)$ are globally Lipschitz.
 - ③ $\exists c \in (1, \infty)$ s.t. $\forall (x, \gamma): 0 < c^{-1} \leq c(x, \gamma) \leq c$.
 - ④ If X is not a Lévy process, then
 $\exists c', M > 0$ s.t. $\forall |x| \geq M: xa(x, \alpha_0) \leq -c'|x|^2$.
- * X is then ergodic under the true image measure P_0 , the invariant measure denoted by $\pi_0(dx)$.

A2. Driving noise

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- ① $\mathcal{L}(Z_1)$ is symmetric around 0, and the Lévy measure ν of Z fulfils

$$\nu(dz) = \exists g_0(z)dz \quad \text{s.t.} \quad g_0(z) = \frac{c_0}{|z|^{1+\beta}} \{1 + O(|z|)\}, \quad |z| \rightarrow 0.$$

- * $\mathcal{L}(h^{-1/\beta}Z_h) \xrightarrow{h \rightarrow 0} \beta$ -stable law with the C.F. $u \mapsto \exp(-|u|^\beta)$ for some $\beta \in (0, 2)$: ϕ_β denotes the density.

- ② $\mathcal{L}(h^{-1/\beta}Z_h)$ admits a positive density $f_h(y)$ s.t.:
There exist constant $\epsilon_n \rightarrow 0$ and Lebesgue-integrable λ s.t.

$$\sqrt{n} \int |f_h(y) - \phi_\beta(y)| dy \rightarrow 0.$$

- * This holds for, e.g., the NIG Z if $nh_n^{2-\kappa} \rightarrow 0$ for some $\kappa > 0$.

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$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- ① $\mathcal{L}(Z_1)$ is symmetric around 0, and the Lévy measure ν of Z fulfils

$$\nu(dz) = \exists g_0(z)dz \quad \text{s.t.} \quad g_0(z) = \frac{c_0}{|z|^{1+\beta}} \{1 + O(|z|)\}, \quad |z| \rightarrow 0.$$

- * $\mathcal{L}(h^{-1/\beta}Z_h) \xrightarrow{h \rightarrow 0} \beta$ -stable law with the C.F. $u \mapsto \exp(-|u|^\beta)$ for some $\beta \in (0, 2)$: ϕ_β denotes the density.
- ② $\mathcal{L}(h^{-1/\beta}Z_h)$ admits a positive density $f_h(y)$ s.t.:
There exist constant $\epsilon_n \rightarrow 0$ and Lebesgue-integrable λ s.t.

$$\sqrt{n} \int |f_h(y) - \phi_\beta(y)| dy \rightarrow 0.$$

- * This holds for, e.g., the NIG Z if $nh_n^{2-\kappa} \rightarrow 0$ for some $\kappa > 0$.

A3. Sampling rate

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- ① $\beta \geq 1$ if X is a Lévy process (we do not need $nh_n \rightarrow \infty$).
- ② Otherwise, $\beta > 1$, $nh_n \rightarrow \infty$, and
 $\exists \epsilon_0 > 0$ s.t. $\limsup_{n \rightarrow \infty} nh_n^{3-2/\beta-\epsilon_0} < \infty$.

A4. Weight function; for heavy-tailed cases

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- ① $W : \mathbb{R} \rightarrow \mathbb{R}_+$ is bounded.
- ② There exists a function $K : \mathbb{R} \rightarrow \mathbb{R}_+$ s.t.
 - ① $\sup_{\theta \in \Theta} W(x) \{ |\partial_\alpha a(x, \alpha)| + |\partial_\alpha a(x, \alpha)|^2 + |\partial_\alpha^2 a(x, \alpha)| + |\partial_\gamma c(x, \gamma)| + |\partial_\gamma c(x, \gamma)|^2 + |\partial_\gamma^2 c(x, \gamma)| \} \leq K(x)$,
 - ② $\sup_{t \in \mathbb{R}_+} E_0[K(X_t)] < \infty$.

A5. Nonsingularity and identifiability

For $g(\mathbf{y}) := \frac{\partial \phi_\beta}{\phi_\beta}(\mathbf{y})$,

$$\textcircled{1} \det \left\{ \int W(\mathbf{x}) \frac{[\partial_\alpha a(\mathbf{x}, \alpha_0)]^{\otimes 2}}{c(\mathbf{x}, \gamma_0)^2} \pi_0(d\mathbf{x}) \right\} \cdot \det \left\{ \int W(\mathbf{x}) \frac{[\partial_\gamma c(\mathbf{x}, \gamma_0)]^{\otimes 2}}{c(\mathbf{x}, \gamma_0)^2} \pi_0(d\mathbf{x}) \right\} \neq 0.$$

$$\textcircled{2} \iint W(\mathbf{x}) \frac{\partial_\alpha a(\mathbf{x}, \alpha)}{c(\mathbf{x}, \gamma)^2} \{a(\mathbf{x}, \alpha_0) - a(\mathbf{x}, \alpha)\} \partial g\left(\frac{c(\mathbf{x}, \gamma_0)}{c(\mathbf{x}, \gamma)} \mathbf{y}\right) \phi_\beta(\mathbf{y}) d\mathbf{y} \pi_0(d\mathbf{x}) = 0$$

iff $\theta = \theta_0$.

$$\textcircled{3} \iint W(\mathbf{x}) \frac{\partial_\gamma c(\mathbf{x}, \gamma)}{c(\mathbf{x}, \gamma)^2} \left\{ 1 + \frac{c(\mathbf{x}, \gamma_0)}{c(\mathbf{x}, \gamma)} \mathbf{y} g\left(\frac{c(\mathbf{x}, \gamma_0)}{c(\mathbf{x}, \gamma)} \mathbf{y}\right) \right\} \phi_\beta(\mathbf{y}) d\mathbf{y} \pi_0(d\mathbf{x}) = 0$$

iff $\theta = \theta_0$.

Construction of our estimator

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t$$

- Again, the naive Euler type approximation:

$$\begin{aligned} X_{jh_n} &\approx^{P_0} X_{(j-1)h_n} + a_{j-1}(\alpha_0)h_n + c_{j-1}(\gamma_0)\Delta_j Z \\ &= X_{(j-1)h_n} + a_{j-1}(\alpha_0)h_n + c_{j-1}(\gamma_0)h_n^{1/\beta} \cdot \frac{\Delta_j Z}{h_n^{1/\beta}} \end{aligned}$$

$$\therefore \epsilon_{nj}(\theta_0) := \frac{\Delta_j X - a_{j-1}(\alpha_0)h_n}{h_n^{1/\beta} c_{j-1}(\gamma_0)} \approx \beta\text{-stable, in law (density } \phi_\beta).$$

- We define our estimator $\hat{\theta}_n = (\hat{\alpha}_n, \hat{\gamma}_n)$ through the quasi-likelihood:

$$\hat{\theta}_n \in \operatorname{argmax}_{\theta \in \Theta} \sum_{j=1}^n W_{j-1} \log \left\{ \frac{1}{h_n^{1/\beta} c_{j-1}(\gamma)} \phi_\beta(\epsilon_{nj}(\theta)) \right\}.$$

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Main claim: Asymptotic Normality

Under the aforementioned assumptions, the estimator is A.N.:

$$\left(\sqrt{nh_n^{1-1/\beta}}(\hat{\alpha}_n - \alpha_0), \sqrt{n}(\hat{\gamma}_n - \gamma_0) \right) \Rightarrow \mathcal{N} \left(\mathbf{0}, \text{diag}[U(\theta_0)^{-1}, V(\theta_0)^{-1}] \right),$$

where

$$U(\theta_0) = \int W(x) \frac{\{\partial_\alpha a(x, \alpha_0)\}^{\otimes 2}}{c(x, \gamma_0)^2} \pi_0(dx) \cdot \int \frac{\partial \phi_\beta(y)^2}{\phi_\beta(y)} dy,$$

$$V(\theta_0) = \int W(x) \frac{\{\partial_\gamma c(x, \gamma_0)\}^{\otimes 2}}{c(x, \gamma_0)^2} \pi_0(dx) \cdot \int \frac{\{\phi_\beta(y) + y \partial \phi_\beta(y)\}^2}{\phi_\beta(y)} dy$$

Remarks

$$dX_t = a(X_t, \alpha)dt + c(X_{t-}, \gamma)dZ_t.$$

Contrast	Rates	
	α	γ
Gaussian QL	$\sqrt{nh_n}$	$\sqrt{nh_n}$
Non-Gaussian (Stable) QL	$\sqrt{nh_n^{1-1/\beta}}$	\sqrt{n}

- GQLE is easier to use, but NGQLE has better performance.
- Both are somewhat robust for the specification of the Lévy measure.
- The technical conditions imposed are, unfortunately, not so mild.
- However, we conjecture that the NGQLE is asymptotically optimal.

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A small numerical example: NIG Lévy process

- We set $X_t = \alpha t + \gamma Z_t$ with $\mathcal{L}(Z_t) = NIG(a, 0, t, 0)$ for some (unknown) $a > 0$, hence

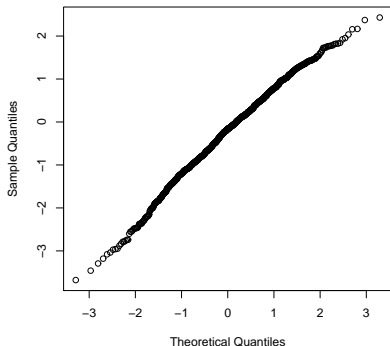
$$\frac{X_t - \alpha t}{\gamma t} \sim NIG(at, 0, 1, 0) \rightarrow^d \text{standard Cauchy.}$$

- $\theta_0 = (\alpha_0, \gamma_0) \leftarrow (-3, 2)$, $\beta = 1$, and $a = 2$.
- 1000 iterations with $n = 500$ and $h_n = 1/n$.
- Results.

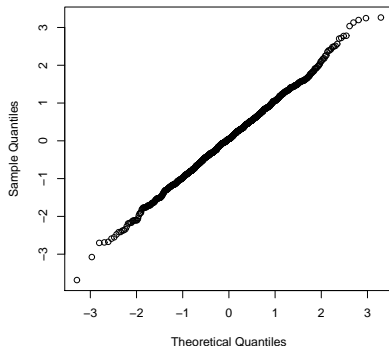
	Sample median	Stable QLE α	Stable QLE γ
Mean	-2.9961	-2.9942	1.9781
S.D.	0.1430	0.1272	0.1237
Max	-2.5186	-2.5852	2.3635
Min	-3.4808	-3.4704	1.6225

Achieving the normality of the NGQLE

Studentized sig QQ plot



Studentized mu QQ plot



Summary and concluding remarks

- **The essential assumption:** $\mathcal{L}(h^{-1/\beta} Z_h)$ is approximately β -stable.
- Without imposing $nh_n \rightarrow \infty$ for all cases?:
A suitable weak limit theorem is necessary for identifying possible limit distribution.
- Want to utilize the Cauchy quasi-likelihood ($\beta = 1$) for SDE.
- Estimation of the Blumental-Gettoor index β :
For Lévy driven OUP, we can apply LAD type estimate (M, 2010).
- Large deviation for the random fields, giving convergence of moments?
- Adaptive estimation for jump SDEs? (Uchida and Yoshida (2010) for diffusions)



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