

# Asymptotics for the focusing integrable discrete nonlinear Schrödinger equation

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# 1. Nonlinear Schrödinger equation and a soliton

**focusing** NLS

$$iu_t + u_{xx} + 2|u|^2u = 0$$

soliton

$$u(x, t) = 2\eta e^{2i\xi x - 4i(\xi^2 - \eta^2)t + i(\psi_0 + \pi/2)} \\ \times \operatorname{sech}(2\eta x - 8\xi\eta t - 2\delta_0)$$

carrier wave (exp, oscillatory)  $\times$  traveling solitary wave (sech)

## 2. Long-time asymptotics of soliton equations

As  $t \rightarrow \infty$ , the solution is asymptotically a sum of solitons plus a small perturbation.

NLS: Fokas-Its '96 (IBVP), Kamvissis '95 (IVP)

Toda lattice: Krüger-Teschl '09 (IVP)

KdV: Tanaka '75 (IVP), Grunert-Teschl '09 (IVP)

**SOLITON RESOLUTION** in recent terminology  
(e.g. Terence Tao's "Why are solitons stable?", 2009)

Valid for non-integrable equations as well,  
but INTEGRABLE ones are particularly important because

- they are model cases
- phase shift can be written down in the inverse scattering parlance.

### 3. Integrable Discrete NLS (IDNLS) 1

NLS (**focusing**)

$$iu_t + u_{xx} + 2|u|^2u = 0$$

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Ablowitz-Ladik ('75)

integrable discrete nonlinear Schrödinger equation (**focusing**)

$$i \frac{d}{dt} R_n + (R_{n+1} - 2R_n + R_{n-1}) + |R_n|^2 (R_{n+1} + R_{n-1}) = 0$$

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Both have solitons:

**carrier wave (exp, oscillatory) × traveling solitary wave (sech)**

## 4. Integrable discrete NLS (IDNLS) 2

$z_1$  **eigenvalue**,  $|z_1| > 1$ ,

$C_1(0)$  **norming constant**

a parameter (to be explained later)

bright soliton

$BS(n, t; z_1, C_1(0))$

= (exp carrier wave)  $\times$  (sech traveling wave)

If we multiply  $C_1(0)$  by another constant

$\Rightarrow$  **PHASE SHIFT** in **exp** and **sech**.

It happens when solitons collide with one another.

## 5. Soliton

$R_n(t) = \text{BS}(n, t; z_1, C_1(0))$ , soliton

$z_1 = \exp(\alpha_1 + i\beta_1)$ ,  $\alpha_1 > 0$ : eigenvalue

$C_1(0)$ : norming constant (at  $t = 0$ )

$\text{BS}(n, t; z_1, C_1(0)) = \text{carrier wave} \times \text{traveling wave}$

$$= \exp(-i[2\beta_1(n+1) - 2w_1t - \arg C_1(0)]) \\ \times \sinh(2\alpha_1) \text{sech}[2\alpha_1(n+1) - 2v_1t - \theta_1].$$

$v_1, w_1$ : written in terms of  $\alpha_1, \beta_1$ .

$\theta_1$ : written in terms of  $|C_1(0)|, \alpha_1$ .

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## 6. Soliton collision and phase shift

**Popular topic in Integrable systems.**

A faster soliton overtakes a slower one.

Velocity and shape are preserved after overtaking.

There may be phase shift, like  $f(x - ct) \mapsto f(x - ct + x_0)$ .

Multiplication of the norming constant by another constant  
 $\Rightarrow$  phase shift

Different constants as  $t \rightarrow \infty$  and  $t \rightarrow -\infty$   
 $\Rightarrow$  phase shift due to collision

Studying phase shift is reduced to studying these constants.

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### TWO GOALS

- Soliton resolution.  
Is the solution asymptotically a sum of 1-solitons?
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Is the solution asymptotically a sum of 1-solitons?
- Calculation of phase shift (as  $t \rightarrow \infty$ )

## 7. IDNLS and its Lax pair

$$i \frac{d}{dt} R_n + (R_{n+1} - 2R_n + R_{n-1}) + |R_n|^2 (R_{n+1} + R_{n-1}) = 0 \quad (\text{IDNLS})$$

.....

$$n\text{-part} : X_{n+1} = \begin{bmatrix} z & \bar{R}_n \\ R_n & z^{-1} \end{bmatrix} X_n$$

$$t\text{-part} : \frac{d}{dt} X_n = \left[ \text{a complicated matrix} \right] X_n$$

(IDNLS) is the compatibility condition.

$z \in \mathbb{C} \setminus \{0\}$  is called the spectral parameter,  
Eigenvalues are its special values.

## 8. Eigenfunctions of the $n$ -part

If  $R_n \rightarrow 0$  (rapidly) as  $n \rightarrow \pm\infty$ , then approximately

$$X_{n+1} \approx \begin{bmatrix} z & 0 \\ 0 & z^{-1} \end{bmatrix} X_n. \quad \text{'solutions' } \begin{bmatrix} z^n \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ z^{-n} \end{bmatrix}$$

There exist eigenfunctions

$\phi_n(z), \psi_n(z)$  in  $|z| \geq 1$  and  $\psi_n^*(z)$  in  $|z| \leq 1$   
which behave like  $z^{\pm n}$  as  $n \rightarrow \pm\infty$ .

3 solutions in the 2-dimensional solution space.

(There's another, but we omit it.)

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## 9. Eigenvalues and the reflection coefficient

On  $|z| = 1$ ,  $\exists a(z)$ ,  $b(z) = b(z, t)$  such that

$$\phi_n(z) = b(z)\psi_n(z) + a(z)\psi_n^*(z),$$

If  $a(z_j) = 0$ , then  $a(-z_j) = 0$ .

$\{\pm z_j, \pm \bar{z}_j^{-1}\}$  is called a quartet of eigenvalues.

It corresponds to a soliton.

On  $|z| = 1$ , the reflection coefficient  $r(z)$  is

$$r(z) := \frac{b(z)}{a(z)}$$



## 10. Reflection coefficient

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---

Recall:  $\psi_n \sim z^{-n} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ,  $\psi_n^* \sim z^n \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  as  $n \rightarrow \infty$ .

$r$  is characterized by

$$r\psi_n + \psi_n^* \sim \text{const.} \begin{bmatrix} z^n \\ 0 \end{bmatrix} \quad (n \rightarrow -\infty).$$

time evolution

$r(z, t) = r(z) \exp(it(z - z^{-1})^2)$ , where  $r(z) = r(z, 0)$ .

## 11. Scattering data

Assume  $a(z_j) = 0$  (order 1).  $\pm z_j$  is an eigenvalue.

$$\phi_n(z_j) = \exists b_j \psi_n(z_j).$$

The **norming constant** is defined by  $C_j := \frac{b_j}{\frac{d}{dz}a(z_j)}$

Scattering Data

$$\{(\pm z_j, \pm \bar{z}_j^{-1}, C_j)\}_{j=1}^J, \quad r(z)$$

The potential  $R_n$  is said to be **reflectionless** if  $r(z) = 0$ .

**Inverse Scattering Transform**

The potential  $R_n$  is reconstructed from the scattering data.  
Done by using a Riemann-Hilbert problem with poles.

## 12. Riemann-Hilbert Problem (RHP)

Boundary value problem on the complex plane

$\Gamma$ : curve (the left-hand side is the + side).

$m(z)$ : unknown matrix, components are holomorphic in  $\mathbb{C} \setminus \Gamma$

*Example:* 1.  $\Gamma = \mathbb{R}$ ,  $m(z)$  is holomorphic in  $\pm \text{Im } z > 0$ .  
2.  $\Gamma = \{|z| = 1\}$ ,  $m(z)$  is holomorphic in  $|z| \neq 1$ .

$m_+, m_-$ : boundary values on  $\Gamma$  from  $\pm$  sides

*RHP:*  $m_+ = m_- v$  on  $\Gamma$  ( $v$ : given, JUMP MATRIX)

No jump if  $v = I$ .  $m$  is analytically continued.

Normalization:  $m(z) \rightarrow I$  as  $z \rightarrow \infty$ .

(ensures uniqueness)

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## 13. RHPs are like integrals

RHP:  $m_+ = m_- v$  on  $\Gamma$

**Deift-Zhou's nonlinear steepest descent is based on**

- **Contour deformation**, introduction of a new unknown and a new jump matrices  
original RHP  $\Leftrightarrow$  new RHP.
- **Continuity**  $v \mapsto m$  is continuous.  
(justification of **perturbation analysis**)
- **Removing a part of the contour**
  1. If  $v = I$  (no jump) on  $\hat{\Gamma} \subset \Gamma$ ,  
 $m[\text{original}] = m[\text{with } \hat{\Gamma} \text{ deleted}]$
  2. If  $v \approx I$  on  $\hat{\Gamma}$ ,  $m[\text{original}] \approx m[\text{with } \hat{\Gamma} \text{ deleted}]$

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## 14. RHP with poles

$m(z)$ : unknown matrix, components are meromorphic in  $\mathbb{C} \setminus \Gamma$ .

RHP:  $m_+ = m_- v$  on  $\Gamma$

$m(z)$  has poles. Residue conditions imposed.

### Inverse Scattering

- The jump matrix written in terms of **the reflection coefficient**.
- The poles of  $m(z)$  are the **eigenvalues**.
- Residue conditions written in terms of the **norming constants**.

The potential can be reconstructed from the solution  $m(z)$  of the RHP.

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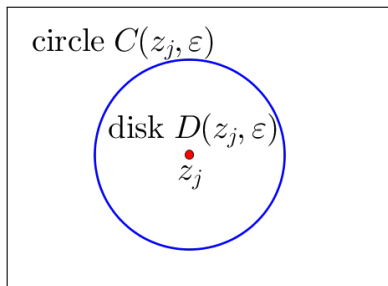


## 15. 'blowup' of poles

$$\text{Res}(m(z); z_j) = \lim_{z \rightarrow z_j} m(z) \begin{bmatrix} 0 & 0 \\ z_j^{-2n} C_j(t) & 0 \end{bmatrix}.$$

Replace a **pole** with a **circle**.

Then one can use the RHPs-are-like-integrals technique.



In the disk  $D(z_j, \varepsilon)$ ,  
subtract the singular part of  $m$ .  
New unknown  $\hat{m}$ .  
holomorphic at  $z_j$ .  
jump along  $C(z_j, \varepsilon)$  instead.

If the jump matrix is close to the identity, it can be ignored.

**Decrease # of poles  $\Rightarrow$  reduction to the 1-soliton case**

## 16. IVP of IDNLS

Time evolution of the scattering data

Eigenvalues are independent of time.

$$C_j(t) = C_j(0) \exp(it(z_j - z_j^{-1})^2),$$

$$r(z, t) = r(z) \exp(it(z - z^{-1})^2) \text{ on } |z| = 1,$$

where  $r(z) := r(z, 0)$

Initial value problem

$R_n(0)$  determines the scattering data at  $t = 0$ .

The scattering data in  $t > 0$  are determined.

Formulate RHP with poles (involving the scattering data).

The potential  $R_n(t)$  ( $t > 0$ ) is reconstructed from the solution of the RHP.

## 17. Reflectionless Case

If  $r(z) = r(z, 0) = 0$ ,  $R_n(t) = \text{multi-soliton}$ .

It approaches a sum of 1-solitons as  $t \rightarrow \infty$ .

phase shift (formal proof in Ablowitz-Prinari-Trubatch '04)

Each term is of the form  $\text{BS}(n, t, z_j, \underbrace{p_j T(z_j)^{-2} C_j(0)}_{\text{phase shift}})$

Phase shift is determined by the eigenvalues:

$$p_j := \prod_{k>j} z_k^2 \bar{z}_k^{-2}, \quad T(z_j) := \prod_{k>j} \frac{z_k^2 (z_j^2 - \bar{z}_k^{-2})}{z_j^2 - z_k^{-2}}$$

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Is soliton resolution valid even if  $r(z) \neq 0$ ?

Q2

How does the reflection affect the phase shift?

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## 18. Main results (sketched)

What happens as  $t \rightarrow \infty$  if there is reflection ( $r(z) \neq 0$ )?  
Some generic assumptions (finite number of eigenvalues, ...)

### SOLITON RESOLUTION

A sum of 1-solitons plus a small perturbation

A new PHASE SHIFT formula involving the REFLECTION COEFFICIENT  $r(z)$ .

$|n|/t < 2$  (the 'timelike' region)

There is a new factor written in terms of  $r(z)$ :  
 $BS(n, t, z_j, \text{New} \cdot p_j T(z_j)^{-2} C_j(0))$

$|n|/t \geq 2$

Leading term is the same as in the reflectionless case.

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## 19. Asymptotic Behavior: $r(z) \neq 0$

♣ **tw** is the velocity of the soliton (traveling wave).

$|\text{tw}(z_j)| < 2$  *Timelike Region: New Phase Shift Formula*

$$R_n(t) = \text{BS} \left( n, t; z_j, \delta(0)\delta(z_j)^{-2} p_j T(z_j)^{-2} C_j(0) \right) + O(t^{-1/2}).$$

$\delta(z)$  determined by  $r(z)$ .

$p_j, T(z_j)$  determined by  $z_k$ 's ( $k \geq j$ ).

$z_k$ 's correspond to the  $j$ -th and faster solitons.

$|\text{tw}(z_j)| = 2$  *Leading term remains the same*

$$R_n(t) = \text{BS} \left( n, t; z_j, p_j T(z_j)^{-2} C_j(0) \right) + O(t^{-1/3}).$$

$|\text{tw}(z_j)| > 2$  *Leading term remains the same*

As  $|n| \rightarrow \infty$ ,

$$R_n(t) = \text{BS} \left( n, t; z_j, p_j T(z_j)^{-2} C_j(0) \right) + O(n^{-k}), \quad \forall k.$$

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## 20. function $\delta(z)$ in the timelike region

In  $|n| < 2t$  (the timelike region),

$$A := \frac{1}{2} \left( \sqrt{2 + n/t} - i\sqrt{2 - n/t} \right).$$

$$S_1 := e^{-\pi i/4} A, \quad S_2 := e^{-\pi i/4} \bar{A}, \quad S_3 := -S_1, \quad S_4 := -S_2.$$

all on  $|z| = 1$ .

**Saddle points** of the phase function to be explained later.

$$\delta(z) := \exp \left( \frac{-1}{2\pi i} \left[ \int_{S_1}^{S_2} + \int_{S_3}^{S_4} \right] (\tau - z)^{-1} \log(1 + |r(\tau)|^2) d\tau \right)$$

$\delta(z)$  is determined by the **reflection coefficient**.

$\delta(z) \equiv 1$  in the reflectionless case.

## 21. RHP with poles and phase function

$$m_+(z) = m_-(z)v(z) \text{ on } |z| = 1$$

$$v(z) = \begin{bmatrix} 1 + |r(z)|^2 & e^{-2\varphi} \bar{r}(z) \\ e^{2\varphi} r(z) & 1 \end{bmatrix} \text{ JUMP MATRIX}$$

$$\varphi = \frac{1}{2}it(z - z^{-1})^2 - n \log z \quad \text{PHASE FUNCTION!}$$

### “Nonlinear Fourier-Laplace analysis”

Residue conditions at the poles of  $m(z)$  written in terms of the norming constants.

Potential reconstruction  $R_n(t) = - \left. \frac{d}{dz} m(z)_{21} \right|_{z=0}$

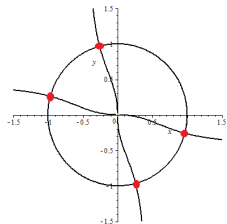
**IVP solved. Asymptotic expansion calculated.**

## 22. Different behaviors in different regions. Why?

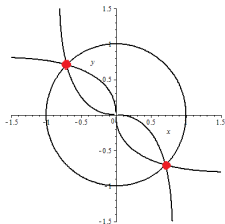
$$\varphi = \frac{1}{2}it(z - z^{-1})^2 - n \log z \quad \text{phase function}$$

$\{\operatorname{Re} \varphi(z) = 0\} \supset \{|z| = 1\}$ . Red dots are stationary points.

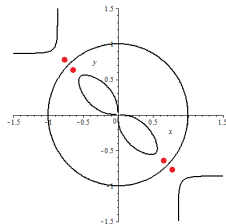
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$$|n| = 2t$$



$$|n| > 2t$$

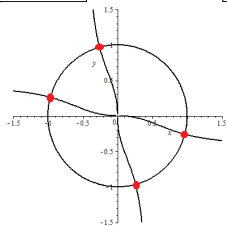


## 22. Different behaviors in different regions. Why?

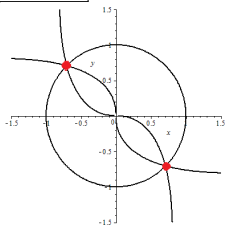
$$\varphi = \frac{1}{2}it(z - z^{-1})^2 - n \log z \quad \text{phase function}$$

$\{\text{Re } \varphi(z) = 0\} \supset \{|z| = 1\}$ . **Red dots** are stationary points.

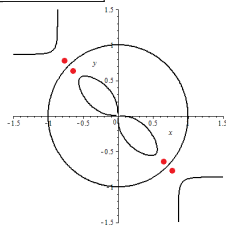
$$|n| < 2t$$



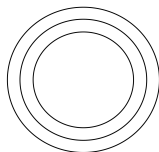
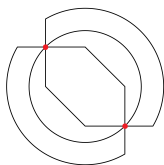
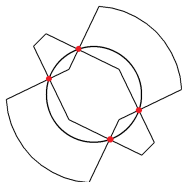
$$|n| = 2t$$



$$|n| > 2t$$



Steepest descent paths.



# Thank you very much.

- Long-time asymptotics for the integrable discrete nonlinear Schrödinger equation: the focusing case, to appear in Funkcialaj Ekvacioj, arXiv:1512.01760 [math-ph]
- (related work) Riemann-Hilbert factorization of matrices invariant under inversion in a circle, to appear in Proc. AMS, Volume 147, Number 5, May 2019, arXiv:1805.12366 [math-ph]