

Classification of unstable travelling wave solutions to KdV type equations

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KdV type eq.

$$\text{(fKdV)} \quad \partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0, \quad (t, x) \in \mathbb{R} \times \mathbb{R}$$

- $u = u(t, x)$: real-valued unknown function
- $1 \leq \sigma \leq 2$, $D_x^\sigma := \mathcal{F}^{-1}|\xi|^\sigma \mathcal{F} = (-\partial_x^2)^{\sigma/2}$ (\mathcal{F} : the Fourier transform)
 $\sigma = 2$ \cdots KdV equation, $\sigma = 1$ \cdots Benjamin–Ono equation

Aim of this study

To observe phenomena of travelling wave solutions to (fKdV)

with nonlinearities $f(u) = u^p + u^q$, where $p, q \in \mathbb{N}$, $2 \leq p < q < \infty$.

Especially, to classify of the phenomena by the parity of indices p and q .

Example $\sigma = 2$, $p = 2$, $q = 3$ \cdots the Gardner equation

(deduced by Miura–Gardner–Kruskal (1968))

Remark We can also consider nonlinearities of the form $f(u) = -u^p + u^q$.

(fKdV)

$$\partial_t u + \partial_x(u^p + u^q) - \partial_x D_x^\sigma u = 0$$

Notation $H^{\sigma/2}$: L^2 -based Sobolev space

Assumption (solvability of (fKdV))

$\forall u_0 \in H^{\sigma/2}$, $\exists T = T(\|u_0\|_{H^{\sigma/2}}) > 0$, $\exists! u(t) \in C([0, T], H^{\sigma/2})$

with conserved energy E and mass M ;

$$E(v) = \frac{1}{2} \|D_x^{\sigma/2} v\|_{L^2}^2 - \frac{1}{p+1} \int_{\mathbb{R}} v^{p+1} dx - \frac{1}{q+1} \int_{\mathbb{R}} v^{q+1} dx,$$

$$M(v) = \frac{1}{2} \|v\|_{L^2}^2$$

Remark This assumption is satisfied if $\frac{4}{3} \leq \sigma \leq 2$. (Shown by Molinet–Tanaka (2025))

(fKdV)

$$\partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0$$

Travelling wave solution $u(t, x) = \phi(x - ct)$ ($c > 0$: wave speed)

The function $\phi \in H^{\sigma/2}$ solves the following stationary problems:

$$(SP) \quad D_x^\sigma \phi + c\phi - f(\phi) = 0, \quad x \in \mathbb{R}$$

The action $S_c(v) = E(v) + cM(v)$

$$\text{where } E(v) = \frac{1}{2} \|D_x^{\sigma/2} v\|_{L^2}^2 - \int_{\mathbb{R}} F(u) dx, \quad F(s) = \int_0^s f(s') ds', \quad M(v) = \frac{1}{2} \|v\|_{L^2}^2$$

We can see that $S_c \in C^2(H^{\sigma/2}, \mathbb{R})$, $S'_c(v) = D_x^\sigma v + cv - f(v)$

Definition $\phi \in H^{\sigma/2}$ is a ground state of (SP)

$$:\iff S_c(\phi) = \inf\{S_c(v) : v \in H^{\sigma/2} \setminus \{0\}, v \text{ is a solution to (SP)}.\}$$

Question 1 The existence of ground states to (SP).

Stability and instability ... Orbital stabilityDefinition

$$\bullet U_r(\phi) = \{v \in H^{\sigma/2} : \inf_{y \in \mathbb{R}} \|u - \phi(\cdot - y)\|_{H^{\sigma/2}} < r\}, \quad \phi \in H^{\sigma/2}, \quad r > 0$$

- A travelling wave $\phi(x - ct)$ is **(orbitally) stable**

$$:\iff \forall \varepsilon > 0 \exists \delta > 0 \text{ s.t.}$$

if $u_0 \in U_\delta(\phi)$, then the solution $u(t) \in C([0, \infty), H^{\sigma/2})$ to (fKdV) exists globally in time and satisfies $u(t) \in U_\varepsilon(\phi)$ for all $t \geq 0$.

- A travelling wave $\phi(x - ct)$ is **unstable** $:\iff$ not stable in above sense.

Question 2 When travelling waves to (fKdV) are stable or unstable?

(fKdV)

$$\partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0$$

(fKdV) with single power nonlinearities $f(u) = u^p$, $p \in \mathbb{N}$, $p \geq 2$.

- Stationary problem with single power nonlinearity

$$D_x^\sigma \psi + c\psi - \psi^p = 0$$

have a unique positive, even ground state ψ_c for each $c > 0$.

(Weinstein (1987), Amick–Toland (1991), Frank–Lenzmann (2013))

- Due to the abstract theory by Bona–Souganidis–Strauss (1987),
 $p < 2\sigma + 1 \implies$ The travelling wave $\psi_c(x - ct)$ is stable for all $c > 0$.
 $p > 2\sigma + 1 \implies$ The travelling wave $\psi_c(x - ct)$ is unstable for all $c > 0$.
- For $\sigma = 2$ and $p = 2\sigma + 1 = 5$ (L^2 -critical KdV eq.)
 The travelling wave $\psi_c(x - ct)$ is unstable for all $c > 0$. (Martel–Merle, 2001)

$$\begin{aligned} \text{(fKdV)} \quad & \partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0 \\ \text{(SP)} \quad & D_x^\sigma \phi + c\phi - f(\phi) = 0 \end{aligned}$$

(fKdV) with double power nonlinearities (our problems)

$$f(u) = u^p + u^q \quad (p, q \in \mathbb{N}, 2 \leq p < q < \infty)$$

Considering non-odd nonlinearities, the existence of travelling waves to (fKdV) varies by the parity of indices p and q .

Existence of nontrivial solutions to (SP) (K., 2024, to appear)

$q \backslash p$	Even	Odd
Even	\exists Positive, even solution \nexists Negative solution	\exists Positive, even solution \exists Negative, even solution if $\sigma = 1, c \ll 1$
Odd	\exists Positive, even ground state \exists Negative, even solution	\exists Positive, even ground state \exists Negative, even ground state

$$(fKdV) \quad \partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0$$

$$(SP) \quad D_x^\sigma \phi + c\phi - f(\phi) = 0$$

(fKdV) with double power nonlinearities (our problems)

$$f(u) = u^p + u^q \quad (p, q \in \mathbb{N}, \quad 2 \leq p < q < \infty)$$

Stability of travelling wave solutions (K., to appear)

Assume q is odd, and let ϕ_c be a positive, even ground state to (SP) for $c > 0$.

- (1) $p < 2\sigma + 1 \implies$ A travelling wave $\phi_c(x - ct)$ is stable for $c \ll 1$.

Example: $(p, q) = (2, 3)$... the Gardner eq.,

$\sigma = 2$, $(p, q) = (3, 5)$... q is L^2 -critical.

and more...

- (2) $q < 2\sigma + 1 \implies$ A travelling wave $\phi_c(x - ct)$ is stable for $c \gg 1$.

Example: $1 < \sigma \leq 2$, $(p, q) = (2, 3)$... the only case for (2)

$$\text{(fKdV)} \quad \partial_t u + \partial_x f(u) - \partial_x D_x^\sigma u = 0$$

$$\text{(SP)} \quad D_x^\sigma \phi + c\phi - f(\phi) = 0$$

Theorem (K., preprint)

Assume q is odd, and let ϕ_c be a positive, even ground state to (SP) for $c > 0$.

(1) $2\sigma + 1 \leq p < q \implies$ A travelling wave $\phi_c(x - ct)$ is unstable for all $c > 0$.

Example: $\sigma = 2$, $(p, q) = (5, 7)$: p is L^2 -critical.

(2) $p < 2\sigma + 1 < q \implies$ A travelling wave $\phi_c(x - ct)$ is unstable for $c \gg 1$.

Example: $1 < \sigma \leq 2$, $p = 3$, q : odd

Remark We can also obtain the classification of unstable travelling waves for (fKdV) with $f(u) = -u^p + u^q$.

Sufficient condition ϕ_c : a ground state of (SP)

Proposition 1

Put $\phi_c^\lambda(x) = \lambda^{\frac{1}{2}} \phi_c(\lambda x)$. (L^2 -norm invariant scaling)

If $\partial_\lambda^2 \mathcal{S}_c(\phi_c^\lambda)|_{\lambda=1} < 0$, then a travelling wave $\phi_c(x - ct)$ is unstable.

With some identities of ϕ_c ,

$$\partial_\lambda^2 \mathcal{S}_c(\phi_c^\lambda)|_{\lambda=1} < 0 \iff \frac{\|\phi_c\|_{L^{p+1}}^{p+1}}{\|\phi_c\|_{L^{q+1}}^{q+1}} < \frac{q+1}{p+1} \cdot \frac{(q-1)\{q - (2\sigma + 1)\}}{(p-1)(2\sigma + 1 - p)} \dots (\star)$$

- $2\sigma + 1 \leq p < q \implies (\star)$ holds for all $c > 0$.
- $p < 2\sigma + 1 < q \implies (\star)$ holds for $c \gg 1$ by approximation.

Lemma 1

ϕ_c : a positive ground state to (SP) for $c > 0$, $\check{\phi}_c(x) = c^{-\frac{1}{q-1}} \phi_c(c^{-\frac{1}{\sigma}} x)$

$\implies \check{\phi}_c \rightarrow \psi_{1,q}$ in $H^{\sigma/2}$ as $c \rightarrow +\infty$,

where $\psi_{1,q}$ is the unique positive ground state of $D_x^\sigma \psi + \psi - \psi^q = 0$.

Hereafter, we assume $\partial_\lambda^2 S_c(\phi_c^\lambda)|_{\lambda=1} < 0$.

Strategy of proof

- Construct a Lyapunov type functional $J_A(\mathbf{v})$ which is bounded in a neighborhood of a ground state ϕ_c
- Under the contradiction assumption that a travelling wave $\phi_c(\mathbf{x} - \mathbf{c}t)$ is stable, find a solution $\mathbf{u}(t)$ to (fKdV) that makes $|J_A(\mathbf{u}(t))|$ diverges as $t \rightarrow +\infty$.
- The proof relies on the variational properties of ground states.

Lyapunov type functional

$$J_A(v) := \int_{\mathbb{R}} v(x + \tilde{z}(v)) \Phi_A(x) dx, \quad v \in U_{\varepsilon_1}(\phi_c), \quad A \geq 1$$

- $\Lambda\phi_c = \frac{1}{2}\phi_c + x\partial_x\phi_c (= \partial_\lambda\phi_c^\lambda|_{\lambda=1}), \quad \Phi(x) = \int_{-\infty}^x \Lambda\phi_c(y) dy$
- $\rho \in C_c^\infty(\mathbb{R}), \quad \rho_A(x) = \rho(x/A) : \text{a cut-off function}, \quad \Phi_A(x) = \Phi(x)\rho_A(x)$
- $\varepsilon_1 > 0, \quad \tilde{z} : U_{\varepsilon_1}(\phi_c) \rightarrow \mathbb{R} : C^2\text{-mapping s.t.}$

$\tilde{z}(\phi_c) = 0, \quad (v(\cdot + \tilde{z}(v)), \partial_x\phi_c)_{L^2} = 0,$ and other properties

(Modulation theory, cf. Bona–Souganidis–Strauss)

$$\implies |J_A(v)| \leq CA^{1/2} \text{ for } v \in U_{\varepsilon_1}(\phi_c)$$

Time derivative of $J_A(u(t))$

$$\frac{d}{dt} J_A(u(t)) = -\langle S'_c(u(t)), \theta_A(u(t)) \rangle_{H^{-\sigma/2}, H^{\sigma/2}}$$

$$\theta_A(v) = \partial_x \Phi_A(\cdot - \tilde{z}(v)) + F_A(v) \partial_x \tilde{z}'(v), \quad F_A(v) = - \int_{\mathbb{R}} v(x) \partial_x \Phi_A(x - \tilde{z}(v)) dx$$

Lemma 2

Put $P_A(v) = \langle S'_c(v), \theta_A(v) \rangle_{H^{-\sigma/2}, H^{\sigma/2}}$.

Then, $\exists A_0 \geq 1$, $\exists \mu_0 > 0$, $\exists \varepsilon_0 \in (0, \varepsilon_1]$ s.t. $S_c(\phi_c) \leq S_c(v) + \mu_0 |P_{A_0}(v)|$

for all $v \in U_{\varepsilon_0}(\phi_c)$.

Key to the proof of Lemma 2

- Variational characterization of ground states

ϕ_c : a ground state to (SP)

$$\iff S_c(\phi_c) = \inf\{S_c(v) : v \in H^{\sigma/2} \setminus \{0\}, K_c(v) = 0\}$$

where $K_c(v) = \langle S'_c(v), v \rangle_{H^{-\sigma/2}, H^{\sigma/2}}$: the Nehari Functional

- Properties of $\Lambda\phi_c$

$$(\phi, \Lambda\phi_c)_{L^2} = 0, \quad \langle S''_c(\phi_c)\Lambda\phi_c, \Lambda\phi_c \rangle_{H^{-\sigma/2}, H^{\sigma/2}} < 0$$

- Convergence of $\theta_A(\phi_c)$

$$\theta_A(\phi_c) \rightarrow \Lambda\phi_c \text{ in } H^{\sigma/2} \text{ as } A \rightarrow +\infty.$$

Here,

$$\theta_A(\phi_c) = \partial_x \Phi_A + F_A(\phi_c) \partial_x \tilde{z}'(\phi_c), \quad F_A(\phi_c) = - \int_{\mathbb{R}} \phi_c(x) \partial_x \Phi_A(x) dx$$

Proof of Proposition 1

Suppose that a travelling wave $\phi_c(\mathbf{x} - \mathbf{c}t)$ is stable.

- $S'_c(\phi_c) = 0$, $\partial_\lambda^2 S_c(\phi_c^\lambda)|_{\lambda=1} < 0 \implies \exists \mu_1 > 0$ s.t. $S_c(\phi_c^{1-\mu_1}) < S_c(\phi_c)$

- By contradiction assumption,

$$\exists u^{1-\mu_1}(t) \in C([0, \infty), H^{\sigma/2}) \text{ with } u^{1-\mu_1}(0) = \phi_c^{1-\mu_1},$$

$$u^{1-\mu_1}(t) \in U_{\varepsilon_0}(\phi_c) \text{ for all } t \geq 0.$$

- By Lemma 2 and the conservation laws,

$$\delta_{\mu_1} := S_c(\phi_c) - S_c(\phi_c^{1-\mu_1}) \leq \mu_0 |P_{A_0}(u^{1-\mu_1}(t))|,$$

$$\text{i.e. } \left| \frac{d}{dt} J_{A_0}(u^{1-\mu_1}(t)) \right| \geq \frac{\delta_{\mu_1}}{\mu_0} > 0$$

$\implies \lim_{t \rightarrow +\infty} |J_{A_0}(u^{1-\mu_1}(t))| = +\infty$, which contradicts the boundedness of J_{A_0} in $U_{\varepsilon_0}(\phi_c)$.

Summary

- We observe conditions where a travelling waves to (fKdV) with $\mathbf{f}(\mathbf{u}) = \mathbf{u}^p + \mathbf{u}^q$ becomes unstable.
- The proof relies on the variational properties of ground states to (SP).

Future works

- Determine whether “nontrivial solutions” to (SP) is a ground state or not.
- Analyze the stability of a travelling wave constructed with an excited state of (SP).
- Observe (fKdV) with $\mathbf{f}(\mathbf{u}) = \pm\mathbf{u}^p - \mathbf{u}^q$.
(The existence of ground states is difficult.)

Thank you for your attention!